

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L2	2	702/1.ccls. and phase and angle and ((linear\$3 or rotation\$3) with displace\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/09/06 12:03
L3	5	702/94.ccls. and phase and angle and ((linear\$3 or rotation\$3) with displace\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/09/06 12:04
L4	8	702/150.ccls. and phase and angle and ((linear\$3 or rotation\$3) with displace\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/09/06 12:05
L5	4	702/151.ccls. and phase and angle and ((linear\$3 or rotation\$3) with displace\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/09/06 12:06
L7	67	"702"/\$.ccls. and phase and angle and ((linear\$3 or rotation\$3) with displace\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/09/06 12:07
L8	13	324/207.24.ccls. and phase and angle and ((linear\$3 or rotation\$3) with displace\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/09/06 12:07
L9	35	324/207.25.ccls. and phase and angle and ((linear\$3 or rotation\$3) with displace\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/09/06 12:08
L10	1	73/1.75.ccls. and phase and angle and ((linear\$3 or rotation\$3) with displace\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/09/06 12:08

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L11	8	73/862.326.ccls. and phase and angle and ((linear\$3 or rotation\$3) with displace\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/09/06 12:10
L12	2	73/862.08.ccls. and phase and angle and ((linear\$3 or rotation\$3) with displace\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/09/06 12:11
L13	8670	phase and angle and ((linear\$3 or rotation\$3) with displace\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/09/06 12:12
L14	711	13 and matrix	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/09/06 12:11
L15	346	14 and sensor	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/09/06 12:12
L16	0	(phase and angle and ((linear\$3 or rotation\$3) with displace\$3) and matrix and quantize\$3 and sensor). CLM.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/09/06 12:13
L17	20	(phase and angle and ((linear\$3 or rotation\$3) with displace\$3) and matrix and quantize\$3 and sensor)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/09/06 12:13
S1	2	"6418388".pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 14:00

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S2	2	"6401052".pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 12:38
S3	2	"5930905".pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 12:43
S4	2	"20060116822"	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 15:13
S5	4	"2005073298"	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 13:07
S7	2	"20040080451"	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 13:10
S8	3	"6816108".pn..	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 13:28
S11	2	702/1.ccls. and phase and (angular with position) and (linear\$3 or rotation\$3 with displacement)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/09/06 12:01
S12	31	702/94.ccls. and phase and (angular with position) and (linear\$3 or rotation\$3 with displacement)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 13:34

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S13	8	702/94.ccls. and phase and (angular with position) and (linear\$3 or rotation\$3 with displacement) and matrix	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 13:35
S14	20	702/150.ccls. and phase and (angular with position) and (linear\$3 or rotation\$3 with displacement) and matrix	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 13:35
S15	2	702/151.ccls. and phase and (angular with position) and (linear\$3 or rotation\$3 with displacement) and matrix	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 13:35
S16	155	"702"/\$.ccls. and phase and (angular with position) and (linear\$3 or rotation\$3 with displacement) and matrix	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 13:44
S17	2	324/207.24.ccls. and phase and (angular with position) and (linear\$3 or rotation\$3 with displacement) and matrix	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 13:45
S18	1	324/207.25.ccls. and phase and (angular with position) and (linear\$3 or rotation\$3 with displacement) and matrix	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 13:45
S19	80	"324"/\$.ccls. and phase and (angular with position) and (linear\$3 or rotation\$3 with displacement) and matrix	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 13:51
S20	0	73/1.75.ccls. and phase and (angular with position) and (linear\$3 or rotation\$3 with displacement) and matrix	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 14:38

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S21	3311	phase and (angular with position) and (linear\$3 or rotation\$3 with displacement) and matrix	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 13:51
S22	1593	S21 and transform\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 13:53
S23	858	S22 and scan\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 13:54
S24	702	S23 and sens\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 13:55
S25	361	S24 and coefficient	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 13:58
S26	12659	angular with position with measure\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 13:58
S27	5	S26 and phase and (linear and rotational with displacement) and matrix and transform\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 13:59
S29	239	wenzler.in.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 14:00

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S30	26	S29 and axel	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 14:01
S31	1	73/862.326.ccls. and phase and (angular with position) and (linear\$3 or rotation\$3 with displacement) and matrix	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 14:38
S32	3	"6816108".pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 15:13
S33	0	"6816108".uref.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/08 15:13